

## Calculation requirements(10')

### Plot details(6')

Shaker Experiment(4 plots total)(1')(include error bars)

**Amplitude vs. Frequency plot (3 length)** (for each plot it should include 2 lines: input & output. Seems like the plot in the lab video)-use shaker.txt data file()

**Wd & wn plot (3length)**(put wd and wn in one plot, it should looks like 6 single points)

Hammer Experiment (18 plots total - 6\*3 different length )(3=6\*0.5')(include error bars)

1. **Voltage vs. Time (Input)** -use hammar**dat**.txt data file
2. **Voltage vs. Time (Output)** -use hammar**dat**.txt data file
3. **Amplitude vs. Frequency (Input)** -use hammar**fft**.txt data file
4. **Amplitude vs. Frequency (Output)** -use hammar**fft**.txt data file
5. **Magnitude of response vs. Frequency** (which is  $|H(f)|$ ) -use hammar**fft**.txt data file
6. **Phase Lag vs. Frequency** (which is  $\arctan(f)$ ) -use hammar**fft**.txt data file

Simulation (8 plots total- 2\*4 effects)(2=4\*0.5')

(Effects of length, damping coefficient, end mass, material type)

1. **Magnitude of Response vs. Frequency**
2. **Phase Angle vs. Frequency**

### Tables(3')

**All experiment items should  $\pm$  uncertainty (4'=6\*0.5'+1'(uncertainty))**

Simulation 3.1-

Length (inches) Theoretical	Frequency(Hz) Simulated	Theoretical Natural Frequency(Hz)
16		
20		
24		

Simulation 3.2-

Damping Coefficient	Theoretical $\omega_n$ (rad/s)	Simulated Natural Frequency (Hz)	Damping Ratio ( $\zeta$ )	Damped Frequency (Hz)
1				
3				
5				
7				
9				

Simulation 3.3.1-

End Weight (kg)	Theoretical Frequency (Hz)	Simulated Natural Frequency (Hz)	Theoretical $\omega_n$ (rad/s)
0.25			
0.40			
0.60			

Simulation 3.3.2-

Material	Theoretical Frequency (Hz)	Simulated Frequency (Hz)	Theoretical $\omega_n$ (rad/s)	Spring Constant $K_{eq}$ (KN/m)
Stainless Steel				
Carbon Steel				
Aluminum				

Shaker Experiment-( $\pm$ uncertainty)

Length of Beam(inches)	Theoretical Natural Frequency $\omega_n$ (rad/s)	Damped Frequency $\omega_d$ (rad/s)	Experimental Natural Frequency (Hz)	Damping Ratio( $\zeta$ )	Spring Constant $K_{eq}$ (KN/m)
$16 \pm 1/64$					
$20 \pm 1/64$					
$24 \pm 1/64$					

Hammer Experiment-( $\pm$ uncertainty)

Length of beam(inches)	Theoretical Natural Frequency $\omega_n$ (rad/s)	Damped Frequency $\omega_d$ (rad/s)	Experimental Natural Frequency (Hz)	Damping Ratio( $\zeta$ )	Spring Constant $K_{eq}$ (KN/m)
$16 \pm 1/64$					
$20 \pm 1/64$					
$24 \pm 1/64$					

Code(5')

Write up (5')

Tips:

where  $x_0$  and  $x_1$  are amplitudes of any two successive peaks.

For system where  $\zeta \ll 1$  (not too close to the critically damped regime, where  $\zeta \approx 1$ ).

$$\zeta \approx \frac{\ln\left(\frac{x_0}{x_1}\right)}{2\pi}$$

$x$  is the magnitude of the systems output.

System Transfer Function:  $H(f) = \frac{\hat{y}(f)}{\hat{x}(f)}$

Where  $\hat{x}(f)$  is the input to the system, and  $\hat{y}(f)$  is the output of the system.

Use fast Fourier transform function-----fft()

$$\hat{x}(f) = \text{fft}(\text{input});$$

$$\hat{y}(f) = \text{fft}(\text{output}).$$

Magnitude of Response:  $|H(f)| = \sqrt{\text{Re}(H(f))^2 + \text{Im}(H(f))^2}$

Phase Lag/Lead:  $\phi(f) = \text{atan}\left(\frac{\text{Im}(H(f))}{\text{Re}(H(f))}\right)$