Compositions are special associations which model a “part-of” or “contained” semantic relationship.

```cpp
Class X {
    // public declarations here
    private:
        Y y;
        Z z;
};
```

In this diagram class X contains objects of classes Y and Z. Classes Y and Z are part-of class X.

Composition is transitive. That is, if class A contains B and class B contains C, then A also contains C.
Aggregation are special associations which model a weak “part-of” or “contained” semantic relationship.

```
Class X {
    // public declarations here
    private:
        Y* pY;  // created in member function
        Z* pZ;  // with new only if needed.
};
```

In this diagram class X holds references to objects of classes Y and Z. Those instances may be part-of class X.
• An object of one class may be used as a data element of another.

• This is called composition. Member objects are used to implement a “part of” relationship.

• The containing class has no special access to contained object’s private data unless it is made a friend. But an object of the containing class can pass initialization data to the contained object during construction.
Inheritance models an “is-a” semantic relationship. Here classes Y and Z inherit from class X.

```
class Y : public X { ... }
class Z : public X { ... }
```

That means that class Y “is-a” class X and the same must be true for class Z. The “is-a” relationship is always a specialization. That is, both classes Y and Z must have all attributes and behaviors of class X, but may also extend the attributes and extend and modify the behaviors of class X.
Inheritance enables the derivation of a new class with almost all the existing methods and data members of its base class.

Derived class functions have access to protected data and functions of the base class.

The derived class “is a” base class object with additional capabilities, creating a new specialized object.
## Derived Class Access Privileges

<table>
<thead>
<tr>
<th></th>
<th><strong>public members</strong></th>
<th><strong>protected members</strong></th>
<th><strong>private members</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>public derivation</strong></td>
<td>public members of base class become public members of derived class</td>
<td>protected members of base class become protected members of derived class</td>
<td>private members of base class are not accessible to derived class</td>
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<td>(stay the same)</td>
<td>(stay the same)</td>
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<tr>
<td><strong>protected derivation</strong></td>
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</tbody>
</table>
Graphics Editor Classes

Diagram showing the hierarchy of graphics objects:
- display
- list
- graphics
- object
- line
- circle
- polygon
Public Inheritance – “is-a”

- **Syntax:** class derived : public base { ... };

- **Public** derivation makes all of the base class functionality available to derived class objects. This has two very important consequences:
  - clients interpret the derived object as a base class object with either specialized, or new capabilities, or both.
  - a derived class object, since it is a base class object, can be used anywhere a base class object can be used. For example, a function typed to accept a base class pointer, or reference, will accept a derived class pointer, or reference in its place.

- New capabilities occur when the derived class adds new member functions or new state members which give the derived object richer state and functional behaviors.

- Specialized capabilities occur when the derived class modifies a base class virtual function.
  - The base class object and derived class object respond to the same message, but in somewhat different ways, determined by the implementations of the virtual function in each class.
  - Because the modified function is qualified in the base class by the keyword virtual, which function is called is determined by the type of object invoking it.
Consider the display list example from the next page. Objects on the list may be any of the types derived from graphicsObject. The display list is said to contain a heterogeneous collection of objects since any one of the graphicsObject types can occur on the list in any order.

The list manager needs to be able to apply one of several specific operations, like draw() or hide(), to every member of the list. However, draw() and hide() processing will be different for each object.

Languages which support object oriented design provide a mechanism called polymorphism to handle this situation. Each object determines for itself how to process draw() or hide() messages.

This powerful mechanism is implemented in C++ using virtual functions. Each derived class redefines the base class virtual draw() and hide() member functions in ways appropriate for its class, using exactly the same signature as in the base class.

We say that the graphicsObject base class provides a protocol for its derived classes by specifying names and signatures of the polymorphic (virtual function) operations.
When a virtual function is redefined in a derived class there are multiple definitions for the same signature, one for each derived class redefinition and often one for the base class as well. Which is called?

Suppose that a base class member function, say

```cpp
virtual void graphicsObj::draw() {...}
```

is redefined by each of the derived graphics objects. If myLine is an instance of the line class, an invocation

```cpp
myLine.draw()
```

will invoke the version defined by the line class.

If, however, a display list object has a list of pointers to base class graphicsObjects, the list can point to any derived object, line, circle, ... and an invocation:

```cpp
listPtr[i] -> draw();
```

will call the draw function of the object pointed to, e.g. line, circle, ..., polygon.
A base class like `graphicsObject` should probably never be instantiated.

This can be prevented by making `graphicsObject` an abstract base class. We do that by defining at least one pure virtual function in the class, e.g.:

```cpp
class graphicsObject {
public:
    virtual void draw() = 0;
    // ... };
```

The `draw() = 0` syntax tells the compiler that `draw` may not be called by a client of this class. This in turn means that no instance of the class can be created. It isn’t widely known that a body may be defined for a pure virtual function, although we usually don’t need to do that.
• No instance of an abstract class can be created. To attempt to do so is a compile time error.

• If a derived class does not redefine all pure virtual functions in its base class it also is an abstract class.

• If all pure virtual functions are properly redefined in the derived class, that is, with exactly the same signatures as in the base class excluding the “= 0” part, then instances of the derived class can be created.

• Abstract base classes are called protocol classes because they provide a protocol or communication standard by which all derived classes must abide.
This example simulates an elevator which visits only two floors. When on the first floor the elevator is stationary until the up button is pressed. It then travels toward the second floor. The arrival event brings the elevator to the second floor. It remains stationary on the second floor until the down button is pressed. It then travels toward the first floor. An arrival event brings the elevator back to the first floor.

This event sequence is described by the state transition diagram shown on the next page. The elevator simulation consists of implementing the state mechanism with one derived class for each state and a global event processing loop.

The base class defines, as member functions, each of the events the system must respond. The base class members all return pointers to themselves without taking any other action. This essentially defines null events.

Derived classes override any event which will cause a transition out of that state by returning a pointer to the next state. So, for example, StateOnFirstFloor over-rider upButton to return a pointer to StateGoingUp. Here again, we see polymorphic operation allowing each state object to determine how it responds to the protocol established by the ElevState base class.
**Elevator States:**

- **OnFirstFloor** → **GoingUp**
- **GoingDown** → **OnSecondFloor**
- **UpButton**
- **DownButton**
- **Arrived**

**Event Loop:**

- **GetEvent**
- **ProcessEvent**

**Class Hierarchy:**

```
ElevState
  ├── StateOnFirstFloor
  │    └── StateGoingUp
  │         └── StateGoingDown
  └── StateOnSecondFloor
```
When a class is publicly derived from a base class most of the base class member functions are inherited along with all the base class data attributes. However, there are a few members which are not inherited:

- **Constructors** must be defined for derived class. They automatically call a base class constructor as their first operation. Derived constructors initialize the new data attributes defined by the derived class and pass initializing values to the base class constructors (see example code demInherit3.cpp).

- **Destructor** must also be defined for the derived class. It should release resources allocated by the derived class. All base class resources are released by the base class destructor which is automatically called by the derived destructor as its last operation.

- **Assignment** operator must be defined for the derived class. An assignment operator should explicitly invoke its base class assignment operator to assign base class data attributes and then assign any derived class data attributes.

Under private inheritance none of the base class operations are accessible (to a client) by default. However, one or more member functions can be made accessible by including in the derived class declaration the expression:

```
   base : baseMemberFunction
```

base is the name of the base class and baseMemberFunction is the name of the base class member function to be made accessible.
Default Members

- Since derived classes do not inherit constructors, the destructor, or assignment operator, these members are created by the compiler if needed.
  - if no constructors are declared by a class, the compiler will define void constructor which is used to build arrays of objects of that class. It does member-wise void constructions. If any other constructor is declared for the class a void constructor will not be defined by the compiler. In this case, declaring an array of objects is a compile time error.
  - if no copy constructor is declared by a class the compiler will define one which does member-wise assignment of data attributes from the copied object to the constructed object. This is used for all call and return by value operations.
  - if no destructor is declared the compiler will define one which performs member-wise destruction of each of the class data attributes.
  - if no copy assignment operator is declared by a class the compiler will define one, if needed, which does member-wise assignment of the class’s data attributes.

- Note that these default operations may not be what is needed by the class. For example, if a class contains a pointer data element, default copying or assignment will result in copying the pointer, not what is pointed to. This is termed a shallow copy. Usually what is wanted is a deep copy. That is, allocating new memory for the pointed to object, copying the object into new memory, and assigning the address of the new object to the pointer data element.
Default Moves

- If no copy constructor, copy assignment, and destructor are declared, then move constructor and move assignment will be implemented by the class.
- The defaults do move operations on the class’s bases and data members.
- As on the previous slide this may not be what you want.
- The design of every class must decide whether to accept the default members, or define those members, or dis-allow them (with the =delete) syntax.
A derived class may have more than one base class. In this case we say that the design structure uses multiple inheritance.

The derived “is-a” base 1 and “is-a” base 2. Multiple inheritance is appropriate when the two base classes are orthogonal, e.g., have no common attributes or behaviors, and the derived class is logically the union of the two base classes.

The next page shows an example of multiple inheritance taken from the iostream module. The class iostream uses multiple inheritance to help provide its behaviors.
Chapter 6 - Hierarchy
Multiple Inheritance (cont)

- A derived class D may inherit from more than one base class:

  ```
  class D : public A, public B, ... { ... };
  ```

- A, B, ... is not an ordered list. It is a set. The class D represents the union of the members of classes A, B, and C.

- If a member mf() of A has the same signature as a member of B, then there is an ambiguity which the compiler will not resolve. Sending an mf() message to a derived object will result in compile time failure unless it is explicitly made unambiguous:

  ```
  d.A::mf();
  ```

- A constructor for D will automatically call constructors for base objects, in the order cited in D’s declaration.

- D’s constructor may explicitly initialize data members of each of the base classes by naming parameterized base constructors in an initialization list:

  ```
  D(Ta a, Tb b, Tc C) : A(a), B(b), C(c) { ... }
  ```
• Suppose we have the situation:

```cpp
class B : public A { ... };  class C : public A { ... };
class D : public B, public C { ... };
```

• Since D contains the attributes of all its base classes, all of the attributes of A are repeated twice in D.
Suppose we have the situation:

```cpp
class B : public A { ... };
class C : public A { ... };
class D : public B, public C { ... };
```

- Since D contains the attributes of all its base classes, all of the attributes of A are repeated twice in D.
Base class constructors are called implicitly by derived class constructors. The B and C constructors are called by D’s constructor.

Who calls A’s constructor?

B will call its A constructor. C will call its A constructor.
We can avoid duplication of A’s members by making it a virtual base class:

```cpp
class B : virtual public A { ... }
class C : virtual public A { ... }
class D : public B, public C { ... }
```

Now an object of the D class contains only one set of base class A’s attributes.
We can avoid duplication of A’s members by making it a virtual base class:

```cpp
class B : virtual public A { ... };
class C : virtual public A { ... };
class D : public B, public C { ... };
```

Who calls A’s constructor? The constructor for B? The constructor for C? C++ resolves the ambiguity by requiring the most derived class to invoke a virtual base class’s constructor. So D’s constructor will construct B and C and A. Note that that sequence is different than for any derivation chain with non-virtual base.
A constructor of a derived class may explicitly initialize its base(s) with the syntax:

\[ B(Ta \ a) : A(a) \ { \ldots \} \]

A virtual base class must be initialized by the most derived constructor, so, for example:

```cpp
class B : virtual public A { \ldots \};
class C : virtual public A { \ldots \};
class D : public B, public C { \ldots \};
```

A will be initialized by:

```cpp
D(Ta \ a, Tb \ b, Tc \ c) : A(a), B(b), C(c) \ { \ldots \}
```

If A were not virtual B’s copy would be initialized by B and C’s copy would be initialized by C.

- **Note that changing a base class from non-virtual to virtual can break correct code.**
End of Presentation