

```

enum thread_type { default_thread, terminating_thread }

typedef Thread<default_thread> thread;
typedef Thread<terminating_thread> tthread;

```

class Thread<thread_type>

private:

```

IThread_Processing* pProc;
HANDLE hThread;
static unsigned int __stdcall threadProc(void *pSelf);
unsigned int _theadID;
thread_priority _priority;

```

using relationship

struct IThread_Processing

```

virtual IThread_Processing* clone()=0;
virtual void run()=0;

```

public:

```

Thread(Thread_Processing& p);
~Thread();
void start();
void wait();
static void wait(HANDLE tHandle);
HANDLE handle();
void sleep(long int Millisecs);
void suspend();
void resume();
thread_priority getPriority();
void setPriority(thread_priority p);
void endThread(unsigned int exit_c

```

// Code Sample:
// - see threads test stub for more details

```

#include "threads.h"

class threadproc : public Thread_Processing<threadproc> {
public:
    threadproc(const std::string& str) : _str(str)
    virtual void run() {
        // define processing for child thread
    }
private:
    std::string _str;      // holds data passed
};

void main() {
    threadproc proc("a string"); // declare derived class
    thread t(proc); // declare thread object
    t.start(); // create a running child thread
    :
    t.wait(); // wait for t to complete
}

```

class Thread_Processing<D>

public:

```

virtual ~processing();
virtual IThread_Processing* clone();

```

class threadproc

private:

```

std::string _str; // parameter needed by run()

```

public:

```

threadproc(const std::string& str) : _str(str) {}
virtual void run() {
    // code to implement your
    // thread processing goes here
}

```

Creating Child Threads